Steady-state shear flows via nonequilibrium molecular dynamics and smooth-particle applied mechanics

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We simulate both microscopic and macroscopic shear flows in two space dimensions using nonequilibrium molecular dynamics and smooth-particle applied mechanics. The time-reversible microscopic equations of motion are isomorphic to the smooth-particle description of inviscid macroscopic continuum mechanics. The corresponding microscopic particle interactions are relatively weak and long ranged. Though conventional Green-Kubo theory suggests instability or divergence in two-dimensional flows, we successfully define and measure a finite shear viscosity coefficient by simulating stationary plane Couette flow. The special nature of the weak long-ranged smooth-particle functions corresponds to an unusual kind of microscopic transport. This microscopic analog is mainly kinetic, even at high density. For the soft Lucy potential which we use in the present work, nearly all the system energy is potential, but the resulting shear viscosity is nearly all kinetic. We show that the measured shear viscosities can be understood, in terms of a simple weak-scattering model, and that this understanding is useful in assessing the usefulness of continuum simulations using the smooth-particle method. We apply that method to the Rayleigh-Bénard problem of thermally driven convection in a gravitational field.

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I. INTRODUCTION

Boltzmann popularized the quest for an understanding of the emergence of irreversibility from time-reversible equations of motion. His explanation made it plain that irreversible behavior can be seen in isolated systems only if fluctuations are ignored—that is, ensemble averages can approach equilibrium even while individual histories continue to cover all available states. Generalizing classical mechanics, admitting interactions with the surrounding world, to include sources and sinks of work and heat, has two advantages: (i) stationary nonequilibrium states can then be generated, and (ii) the analysis of irreversibility becomes less difficult. Several methods for treating time-reversible heat reservoirs have established that the irreversibility associated with the conversion of work to heat is rooted in the chaotic instability of the underlying motion equations [1,2]. The Green-Kubo theory [3], which predicts irreversible behavior in terms of the ensemble average of equilibrium correlation functions, is a general demonstration of the possibility of obtaining irreversible behavior from reversible motion equations.

It has been widely accepted that the Green-Kubo theory predicts some kind of divergence for two-dimensional transport coefficients [4]. The diffusion coefficient, viscosities, and heat conductivity were all expected to diverge because the corresponding correlation integrals decay slowly in two dimensions, inversely as the time. On the other hand, recent high-precision simulations [5] of shear flow, for a short-ranged steep repulsive potential produced a size-independent, though rate-dependent, shear viscosity fairly close to the predictions of Gass' two-dimensional Enskog theory [6]. The reproducible finite nature of these viscosities could be made understandable if the coefficients only diverge in some unobtainable zero-rate large-system limit. Evidently, the simple Green-Kubo derivation of divergence fails to hold for finite systems with finite steady nonequilibrium fluxes. The simulations we report here, for a very different potential, show no problems in defining and using viscosity in two dimensions and cast doubt on the generality of the divergence argument.

An interesting additional puzzle emerged when we began to use smoothed-particle methods to solve analogous flow problems in continuum mechanics. In this approach [7] the equations of continuum mechanics are smoothly interpolated in space, using summed contributions from a set of moving material points. The continuum field variables—stress, energy, strain rate, and heat flux—anywhere in space are calculated by superposing the contributions from all those moving points, which lie within the range of a weight function which describes the "smoothing." At a given space point the superposed averages usually involve contributions from a few dozen of the moving points.

If the continuum material we choose to model happens to be a two-dimensional ideal gas, then the corresponding inviscid Euler equations have as their smooth-particle representation the motion of particles obeying the usual equations of molecular dynamics, with the weight function playing the role of an interatomic potential [8]. Thus, the smooth-particle approach to continuum
mechanics produces another version of the paradox
Boltzmann studied: linking reversible particle motion
equations to irreversible macroscopic behavior [9].

Though the irreversibility problem is an old one, the
capacity and speed of present day computers makes this a
good time to investigate all these questions anew, begin­
ning with both equilibrium Green-Kubo and nonequi­
lbrium steady-state Couette flow simulations of two­
dimensional viscosities, and then applying the results to
the simulation of a two-dimensional unstable flow, the
Rayleigh-Bénard problem. In Sec. II, we introduce the
smooth-particle approach to continuum simulations,
stressing the parallels linking this continuum approach to
molecular dynamics in the case that the macroscopic
weight function is proportional to the microscopic poten­
tial function. Because the atomistic view is unique, and
underlies the continuum one, we next consider atomistic
particles, describing in Sec. III how the continuum con­
tinuous equations, including the mass
conservation

\[ \frac{dp}{dt} = -\rho \nabla \cdot v; \]
\[ \rho \frac{dv}{dt} = \nabla \sigma; \]
\[ \rho \frac{de}{dt} = \sigma : \nabla v - \nabla \cdot Q. \tag{2.1} \]

The method, often called smooth-particle “hydrodynam­
ics,” can be applied to solids as well as to fluids. It treats
the motion of \( N \) “smoothed,” or “smeared-out,” par­
ticles, distributed in space. All the field variables in the
continuum conservation equations, including the mass
density \( \rho \), the velocity \( v \), the energy per unit mass \( e \), the
stress tensor \( \sigma \), and the heat flux vector \( Q \), are inter­
polated among the locations of the moving particles. In the
simplest form of the theory, the density at any point in
space, \( \rho(x) \), is given by the summed contribution of all
particles within range of that point:

\[ \rho(x) = \rho(x) = m \sum_j w(r_j - x) = m \sum_j w(r_j); \quad r_j = x_i - x_j. \tag{2.3} \]

The motion of particle \( i \) is governed by the stress tensor
and the “weighting,” or “smearing,” or “smoothing”
function \( w(r) \), in a sum over all nearby particles \( j \):

\[ d^2x_i/dt^2 = \sum_j \left[ (m \sigma/p^2)_j + (m \sigma/p^2)_i \right] \cdot \nabla_j w(r_{ij}) \tag{2.4} \]

where the stress \( \sigma \) at each particle is calculated from its
internal energy per unit mass, \( e \) (which obeys a similar
equation) and its mass density \( \rho \).

We use a special weighting function, \( w(r) = w_{Lucy}(r) \),
in this work. It is typical of such functions, being
smooth, monotone decreasing with increasing \( r \), and
designed to include interactions between each particle
and a few tens of nearby neighbors. It was used by Lucy
[11], who, with Monaghan [7], invented the smoothed­
particle method in 1977. This Lucy weight function has
circular symmetry, and exactly the same analytic form,
apart from the units, as does the Lucy potential function
which we use in Sec. IV:

\[ w_{Lucy}(r < h = \frac{3}{2} \sigma) = (5/2h^2\pi) [1 + \frac{3}{2}(3r/h)] [1 - (r/h)^3]. \tag{2.5} \]

We arbitrarily choose the cutoff, or range, of this func­
tion to be \( h = 3\sigma \). The multiplicative constant
\((5/2h^2\pi)(5/9\pi\sigma^2)\) is then fixed by the two-dimensional
normalization of \( w \) as

\[ \int 2\pi rw dr = 1. \]

Note that a scalar equation of state, for a two­
dimensional ideal gas,

\[ -\alpha_{xx} = -\alpha_{yy} = P = \rho e = P_0(p/p_0)^2/2, \tag{2.6} \]

(\( P_0 = \epsilon/\sigma^2 \) and \( \rho_0 = m/\sigma^2 \) are constants) provides
equations of motion isomorphic to the motion equations
of monatomic molecular dynamics [7],

\[ m \dot{r}_i = m \dot{r}_i = -\nabla \Phi; \tag{2.7} \]

where \( \phi(r) \) is the pair potential. These equations consti­
tute an autonomous set, with a solution independent of
the energy equation. [The energy equation (2.1), with \( Q \)
set equal to 0, is, however, fully consistent with the dy­
namics generated by (2.7).] Thus, the smooth particles,
whose motion is governed by the ideal gas pressure ten­
sor, through the weighting function \( w(r) \), trace out the
same trajectories as would atomistic particles governed,
through the corresponding potential function \( \phi(r) \), by
the equations of molecular dynamics. For definiteness,
we continue with our special, though typical, choice of the
potential corresponding to our smooth-particle weight­ing
function, using again the functional form introduced
by Lucy: \( \phi_{Lucy}(r) = (\sigma^2)w_{Lucy}(r) \). Potential functions de-
derived from weighting functions, such as this, differ, in shape, range, and units, from conventional pair potentials \( \phi(r) \). Because the smoothed-particle function has no strongly repulsive core and is also relatively long ranged, each smoothed particle simultaneously interacts, weakly, with dozens of others. The statistical mechanics and hydrodynamics of corresponding long-ranged molecular systems, with pair potentials resembling Lucy’s weighting function, have not yet been systematically explored.

Energy is reckoned a little differently in the microscopic and macroscopic dynamics. In the smooth-particle density and energy sums, the self-contribution of each particle, proportional to \( w(0) \), is included. In the molecular dynamics simulations of Sec. IV, the corresponding contributions to the energy,

\[
\{ \phi_{\text{Lucy}}(r_{ij} = 0) = (\varepsilon \sigma^2) \omega_{\text{Lucy}}(0) = (\varepsilon \sigma^2 / \pi h^2) = 0.176838 \varepsilon \},
\]

are not included. This difference does not affect the isomorphism of the two kinds of particle trajectories, since \( w'(0) \) and \( \phi_{\text{Lucy}}(0) \) both vanish.

In this paper, we apply molecular dynamics, equivalent to ideal-gas smoothed-particle applied mechanics, to the analysis of simple two-dimensional flows. We consider first plane Couette flow and then convective Rayleigh-Bénard flow, in which convection rolls, driven by heating in a gravitational field, compete with conduction, as a mechanism for heat transfer. The lack of viscosity for the continuum ideal-gas version of this model suggests that the corresponding flows describe the large-Reynolds-number limit of turbulence analyses [12–14]. It is paradoxical that there is an intrinsic atomic viscosity present in the implementation of this continuum model, which prevents that model’s Reynolds number from diverging.

Movies of smoothed-particle flows reveal high-frequency velocity fluctuations, which are ordinarily absent in continuum mechanics. Because the particles can be large, the smooth-particle simulation method has a substantial scale advantage over molecular dynamics.

### III. SIMULATION OF STEADY TWO-DIMENSIONAL PLANE COUETTE FLOW

Homogeneous periodic shear has been studied for more than 20 years [2,5,15]. In such a flow, an \( N \)-particle system is driven by the motion of neighboring periodic image systems, as shown in Fig. 1. From the macroscopic standpoint, and confirmed by the microscopic equations of motion, the sheared system would steadily gain energy, and heat up, due to this periodic boundary driving. To avoid this heating, and to obtain a nonequilibrium steady state, it is usual to add time-reversible Gauss [16] or Nosé-Hoover [17,18] “friction coefficients” \( \zeta \) to the equations of motion. The resulting reversible friction constrains or controls either the temperature or the internal (excluding the macroscopic flow kinetic energy) energy.

For two-dimensional particles of mass \( m \), and with a macroscopic strain rate \( \dot{\varepsilon} = du_x / dy \), the Gaussian isoenergeticit form of these equations that we use here is the set

\[
\begin{align*}
\dot{x} &= \dot{y} = (p_x / m) ; \\
\dot{y} &= (p_y / m) ; \\
\dot{p}_x &= F_x - \dot{\varepsilon} p_y - \zeta p_x ; \\
\dot{p}_y &= F_y - \dot{\varepsilon} p_x ,
\end{align*}
\]

with

\[
\zeta = -\dot{\varepsilon} p_{xy} V / 2K ; \quad K = (1 / 2m) \sum p^2 .
\]

In our numerical simulations we derive the interparticle forces in the motion equations \( \{(F_x, F_y) = -\nabla \Phi \} \) from the specially chosen short-ranged Lucy pair potential shown in Fig. 2:

![](image)

**FIG. 1.** Two-dimensional \( L \times L \) plane Couette shear flow driven by the relative motion of periodic images (shown dashed). This periodic driving, “Lees-Edwards boundary conditions,” is augmented by a global ergostat in order to generate a nonequilibrium steady state.

**FIG. 2.** Lucy potential function, \( \phi_{\text{Lucy}} \), proportional to the weighting function which we use in our smooth-particle applied mechanics simulations here. The integral of the weighting function is normalized to unity. The force from the Lucy potential vanishes quadratically at the cutoff. In our two-dimensional simulations, each fluid particle interacts with approximately 30 others.
for each pair of particles closer than the cutoff distance.

The reason for this particular choice, which contains the energy scale $\varepsilon$, the length scale $\sigma$, and the cutoff range $h$, is described more fully in Sec. IV. As usual, the total potential energy $\Phi$ is a sum of pair contributions $\phi_{ij}$, one for each pair of particles closer than the cutoff distance. Throughout this work, we arbitrarily choose the range of the potential, $h$, equal to $3\sigma$ and the volume per particle equal to $\sigma^3$, giving the relations $h = 3\sigma = (V/N)^{1/3}$. Here $N$ is the number of particles in the simulation and $V$ is the volume. As before [5], we use the linked-list method in combination with Lees-Edwards boundary conditions for the integration of the equations of motion.

IV. SHEAR VISCOSITIES FOR LUCY'S FORM OF $\phi(r)$ AND $w(r)$

It is convenient to solve the set of $4N$ motion equations for $\{x, y, p_x, p_y\}$ using the classic fourth-order Runge-Kutta method. We have previously simulated the viscous properties for a short-ranged steeply repulsive force using this method [5]. Here, the quadratic nature of our force cutoff implies discontinuities in the forces, proportional to $dt^2$, leading to local single-step trajectory errors of order $dt^4$. These exceed the Runge-Kutta integration error, which is of order $dt^5/5!$. With a time step of $0.005(m:\sigma^2/\varepsilon)^{1/2}$, the single-step energy is still conserved to about 12 digit accuracy. This small energy error can be eliminated by rescaling the momenta after each Runge-Kutta integration step.

All of our simulations have been carried out at unit reduced density, $N:\sigma^2 = V$. This choice gives 24 interacting neighbors for each particle when the particles are arranged in a regular square lattice and 36 interacting neighbors when the particles are arranged in a regular triangular lattice. We use two different energies, $N:\varepsilon/2$ and $N:\varepsilon$. It turns out that in the first lower-energy case, the energy is mainly potential, with $kT = 0.07\varepsilon$, less than half the potential height, $(\varepsilon:\sigma^2)\omega(0) = \phi(0) = 5\varepsilon/(9\pi)$. The higher-energy case, with $E = \Sigma m [e + (u^2/2)] = N:\varepsilon$, corresponds to a thermal energy $kT = 0.54\varepsilon$, three times the maximum value of the potential.

Typical instantaneous configurations of 1024 smoothed Lucy particles are shown in Fig. 3 for the two choices of the total energy, $N:\varepsilon/2$ (left) and $N:\varepsilon$ (right), at the moderately high strain rate, $\dot{\varepsilon} = (\varepsilon/m:\sigma^2)^{1/2}$. Although they appear to be very similar, a striking difference can best be displayed by using an analysis of these structures, suggested to us by Davé. If the local dyadic sum at $r$,

$$S^x_{Dav\varepsilon}(r) = \sum \Delta y_i \Delta y_j \omega(r_i - r) ;$$
$$S^y_{Dav\varepsilon}(r) = \sum \Delta x_i \Delta x_j \omega(r_i - r) ;$$
$$S^z_{Dav\varepsilon}(r) = S^x_{Dav\varepsilon}(r)$$

resembling a moment-of-inertia tensor, is diagonalized, and a path is traced out in the direction of the eigenvector belonging to the minimum eigenvalue, the system is neatly divided into a set of cells, as is shown in Fig. 4.

To draw these pictures, $N$ points on a regular grid covering the simulation box were chosen as starting points for paths of 200 iterations and a step size of $0.1\sigma$ per iteration. The sign of the eigenvector at the initial points was chosen randomly. At any point farther along the path it was chosen such that the scalar product of the eigenvectors for successive steps be positive. The last 150 iterations were used in constructing Fig. 4. Motion along the paths can be viewed as a constant-speed “flow” with characteristic strain-rate-dependent mean-squared displacements, $(\langle \Delta x \rangle^2)$ and $(\langle \Delta y \rangle^2)$. The $x$ and $y$ directions are, respectively, parallel and perpendicular to the flow. This idea is used in Fig. 5 for the same two examples. Each curve is an average over at least 150 instantaneous configurations (taken at intervals of 200 Runge-Kutta time steps). The limiting slopes of these curves correspond to strain-rate-dependent “diffusion coefficients,” but with units of $\sigma$, because the “time” along the path is measured in $\sigma$ units. At unit reduced strain rate, we find $\{D^x, D^y\}$ is $[1.05, 3.83]$ for $E = N:\varepsilon/2$ and $[1.00, 3.21]$ for $E = N:\varepsilon$. As one might expect, the mean-squared displacement in the shear direction is practically energy independent, but varies significantly in the perpendicular direction.

The structural anisotropy introduced by the shear-
\[
\phi_{\text{Lucy}}(r) = (5\varepsilon \sigma^2 / h^2 \pi)[1 + (3r / h)] \\
\times [1 - (r / h)]^3 \quad \text{for } r < h = 3\sigma. \quad (3.4)
\]

The reason for this particular choice, which contains the energy scale \(\varepsilon\), the length scale \(\sigma\), and the cutoff range \(h\), is described more fully in Sec. IV. As usual, the total potential energy \(\Phi\) is a sum of pair contributions \(\phi_{ij}\), one for each pair of particles closer than the cutoff distance. Throughout this work, we arbitrarily choose the range of the potential, \(h\), equal to \(3\sigma\) and the volume per particle equal to \(\sigma^3\), giving the relations \(h = 3\sigma = 3(V/N)^{1/3}\).

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The higher-energy case, with \(E = \Sigma m [v + (v^2 / 2)] = N\varepsilon\), corresponds to a thermal energy \(kT \approx 0.54\varepsilon\), three times the maximum value of the potential.

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\[
S_{\text{Dave}}^{xy}(r) = \sum \Delta y_j \Delta y_j w(r_j - r) \\
S_{\text{Dave}}^{yx}(r) = \sum \Delta x_j \Delta x_j w(r_j - r) \\
S_{\text{Dave}}^{yx}(r) = S_{\text{Dave}}^{xy}(r) = -\sum \Delta x_j \Delta y_j w(r_j - r) \\
\Delta r_j = r_j - r;
\]

resembling a moment-of-inertia tensor, is diagonalized, and a path is traced out in the direction of the eigenvector belonging to the minimum eigenvalue, the system is neatly divided into a set of cells, as is shown in Fig. 4.

To draw these pictures, \(N\) points on a regular grid covering the simulation box were chosen as starting points for paths of 200 iterations and a step size of 0.1\(\sigma\) per iteration. The sign of the eigenvector at the initial points was chosen randomly. At any point farther along the path it was chosen such that the scalar product of the eigenvector for successive steps be positive. The last 150 iterations were used in constructing Fig. 4. Motion along the paths can be viewed as a constant-speed “flow” with characteristic strain-rate-dependent mean-squared displacements, \((\Delta x)^2\) and \((\Delta y)^2\). The \(x\) and \(y\) directions are, respectively, parallel and perpendicular to the flow. This idea is used in Fig. 5 for the same two examples. Each curve is an average over at least 150 instantaneous configurations (taken at intervals of 200 Runge-Kutta time steps). The limiting slopes of these curves correspond to strain-rate-dependent “diffusion coefficients,” but with units of \(\sigma\), because the “time” along the path is measured in \(\sigma\) units.

At unit reduced strain rate, we find \(\{D_x, D_y\} = \{1.05, 3.83\}\) for \(E = N\varepsilon / 2\) and \(\{1.00, 3.21\}\) for \(E = N\varepsilon\). As one might expect, the mean-squared displacement in the shear direction is practically energy independent, but varies significantly in the perpendicular direction.

The structural anisotropy introduced by the shear-
Mean squared displacement

\[
\begin{align*}
\text{y, 0.5} & \quad 70 \\
\text{x, 0.5} & \quad 50 \\
\text{E/N = 1.0} & \\
\text{E/N = 0.5} & \\
\end{align*}
\]

Iteration

FIG. 5. Mean-squared displacements, divided by \( \sigma^2 \), for the artificial "flow" used to characterize the topology of sheared systems. The shearing motion is parallel to the x axis. Both the direction of the measured displacements (x or y) and the reduced strain rate (0.5 or 1.0) have been used to label the curves. Each "iteration" corresponds to a path increment of 0.1 \( \sigma \), as described in Sec. IV.

Mean squared displacement

\[
\begin{align*}
\text{y, 0.5} & \quad 80 \\
\text{x, 0.5} & \quad 50 \\
\text{y, 1.0} & \quad 30 \\
\text{E/N = 1.0} & \\
\text{E/N = 0.5} & \\
\end{align*}
\]

Iteration

FIG. 6. Combined mean-squared displacements (x plus y), divided by \( \sigma^2 \), as a function of energy for the equilibrium zero-strain-rate case.

The trajectories traced out by the particles are exactly the same, whether molecular dynamics, or smooth-particle continuum mechanics is used. Likewise, the kinetic part of the shear pressure-tensor component according to molecular dynamics, \( \langle \sum P_x P_y \rangle \), corresponds to the negative of a volume-averaged Reynolds stress in the continuum, \( \langle -\rho v_x v_y \rangle \), measured in the comoving frame. On the other hand, the potential part

\[
\eta = \frac{-P_{xy}}{\varepsilon}
\]

of \( 0.01 \langle \varepsilon / m \sigma^2 \rangle^{1/2} \) and that the viscosity is sensitive to temperature, varying roughly as \( T^{3/2} \) in the range considered here. An extremely interesting feature of the data at the higher energy, \( E = N \varepsilon \), is an instability occurring in the strain-rate range \( \varepsilon \approx (0.010 \pm 0.002) \langle \varepsilon / m \sigma^2 \rangle^{1/2} \). Though we have not investigated this instability in exhaustive detail, its symptom is that a single particle fairly rapidly attains most of the system kinetic energy. The instability is presaged by dramatic fluctuations in the shear stress \( \langle -\sum P_x P_y / m V \rangle \).

We have carried out a wide range of calculations in order to determine the viscous response of Lucy's fluid as a function of strain rate at two different energies. The resulting pressure tensors and potential energies (omitting the contributions from the self-term at \( r = 0 \)) are given in Tables I and II. The rate-dependent shear viscosities, \( \eta = -P_{xy} / \varepsilon \) from these data are displayed in Fig. 7. In Fig. 8, we show also the normal stress function, \( \langle P_{xx} - P_{yy} \rangle / \varepsilon^2 \). The data indicate that the Lucy "fluid" exhibits noticeable shear thinning at strain rates in excess

FIG. 7. Dependence of shear viscosity, divided by \( (m \varepsilon)^{1/2} / \sigma \), on strain rate for \( E = N \varepsilon \) and \( E = N \varepsilon / 2 \). These results are for thermostatted systems of 1024 Lucy particles. Note the instability, discussed in the text, at reduced strain rates near 0.01 in the higher-energy case.
of the molecular stress has no simple continuum analog. In most of the cases appearing in Tables I and II this contribution to the shear stress is barely significant. 

The small-strain-rate viscosities found at the two energies considered can be estimated on the basis of a simple argument. Imagine that the thermal velocity, \( (kT/m)^{1/2} \), is gradually degraded by a fluctuating random force \( F_{\text{random}} \) (which would vary as the mean slope of the Lucy potential function multiplied by the square root of the number of interacting neighbors). Because the direction of this force is random, the decay time should vary as the square of the ratio \( (kT/m)T_{\text{kin}}/F_{\text{random}} \). The resulting estimate for the kinematic viscosity, \( \lambda T/3 \), where \( \lambda \) is the mean free path, turns out to vary as \( T^{3/2} \). This argument describes the temperature dependence of our viscosities very well and also provides semiquantitative agreement with the numerical values

\[
\eta = 35 (m k T)^{1/2} (kT/\epsilon \sigma^2) ,
\]

restricted to the case of unit density number, \( \sigma^2 = V \).

### Table I

<table>
<thead>
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<th>( N )</th>
<th>( t/\tau )</th>
<th>( \epsilon )</th>
<th>( \langle \Phi/\epsilon \rangle )</th>
<th>( \langle P_{xx} \rangle )</th>
<th>( \langle P_{yy} \rangle )</th>
<th>( \langle P_{yy} \rangle )</th>
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### Table II

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<th>( \epsilon )</th>
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We expect that a similar argument would provide an effective heat conductivity for the Lucy potential, but we have not checked this notion.

V. GREEN-KUBO CORRELATION FUNCTIONS FOR LUCY'S WEIGHT FUNCTION

We found that the Green-Kubo integrand for shear viscosity, shown in Fig. 9, requires extremely long simulation times for convergence. The convergence is evidently not even relevant [4,5] for times greater than \( dt/\varepsilon \), although the plotted data suggest that exponential decay is an accurate representation for times from about \( 5(m/\varepsilon)^{1/2} \) to \( 80(m/\varepsilon)^{1/2} \). The canonical-ensemble Green-Kubo expression for shear viscosity [3,5,19] is

\[
\eta = (V/kT) \int_0^\infty \langle P_{sh}(0)P_{sh}(t) \rangle_{\text{equilibrium}} dt,
\]

where the time-dependent pressure components \( P_{sh} \) can represent either \( P_{xy} \) or \( (P_{xx} - P_{yy})/2 \) in two dimensions. By comparing the two correlation functions for \( P_{xy} \) and \( (P_{xx} - P_{yy})/2 \), an idea of the uncertainties results. This comparison, and the long simulation times required to obtain the correlation function, suggests that nonequilibrium methods are much more efficient than the Green-Kubo approach for this soft Lucy potential.

Many theoretical investigations, summarized in Ref. [4], have concluded that two-dimensional transport coefficients are ill defined, based on the large-system divergence of the corresponding Green-Kubo expressions. On the other hand, our own investigations, past [5,15] and present, show that the two-dimensional viscosity is apparently well defined in a homogeneously ergostatted large-system "hydrodynamic limit."

The situation is still somewhat unclear, at least to us. Our own viscosity work, along with that of others [20], as well as diffusion studies, in systems with rigid boundaries, of Bocquet [21], all suggest no divergence of transport coefficients for large two-dimensional systems. Bocquet and Barrat have recently published their theoretical and computational studies of boundary effects on transport in three dimensions [22]. Their two-dimensional work is in preparation.

We imagine that the theoretical predictions of divergence reflect the relative importance of fluctuations in two dimensions. In two dimensions, both boundaries and fluctuations produce effects of order \( N^{1/2} \). This fact led us to study the boundary dependence of mean-squared-displacement divergence in two-dimensional crystals [15,23]. We found that this quantity diverges logarithmically for both types of boundaries, periodic and rigid, although with slightly different coefficients. It appears to us that viscosity is a useful concept in two dimensions, as it is in three. Viscosity only becomes well defined in a large-system limit which incorporates thermostats, or ergostats, to ensure a homogeneous steady state.

VI. RAYLEIGH-BÉNARD PROBLEM FOR TWO-DIMENSIONAL IDEAL GASES

What is Rayleigh-Bénard instability? If a fluid expands when heated, then the effect of gravitational forces on the resulting density gradient can lead to convection currents [24]. These convection currents, when excited, typically transport heat somewhat more efficiently than does quiescent conduction. The dependence of the problem on temperature leads to two noticeable transitions. For a nearly incompressible fluid, these transitions can be described in terms of the dimensionless Rayleigh number

\[
R = g(\partial \ln V/\partial T_p)(\Delta T/L)L/4/(D\nu),
\]

where \( L \) is the cell height, \( D \) is the thermal diffusivity, \( D = \kappa/(\rho c) \), with \( c \) the specific heat, and \( \nu \) is the kinematic viscosity, \( \nu = (\eta/\rho) \). The gravitational acceleration \( g \) is
discussed below. At the critical Rayleigh number, steady convection currents form. At a considerably higher Rayleigh number, the flow becomes chaotic.

The Rayleigh-Bénard problem has been both discussed and solved, in many ways [24-27], both analytic and numerical. We imitate the conditions of a recent numerical Boltzmann-equation calculation [26] in which the material is a low-density ideal gas. We found it simpler to solve the continuum equations numerically than to attempt to extract a numerical solution from the theoretical work in Refs. [24,27]. We focus on densities and temperatures near unity.

If we consider the twin effects of gravitation and a parallel temperature gradient, the vertical accelerations can be chosen to minimize density variations:

\[ \rho g + \left( \frac{\partial P}{\partial T} \right)_T \frac{dT}{dy} = 0 \Rightarrow g = k \Delta T / (mL). \]  

We further choose the temperature difference between the upper and lower walls equal to the mean temperature, \( \Delta T = T \), so that the Rayleigh number becomes

\[ R = [k \Delta T / (mL)] \Delta T / L \frac{1}{4} / (Dv) = (L^2 kT / m) / (Dv). \]  

Chandrasekhar's analysis [24] (see also Ref. [27]) establishes that quiescent heat flow becomes unstable to convection if the Rayleigh number exceeds a critical value \( R_c \). With the horizontal boundaries at the top and bottom of the convection cell free of friction, \( R_c \) is 658. With these boundaries rigid, with vanishing normal and tangential velocity components, the critical value is \( R_c = 1708 \). We choose periodic vertical boundaries (rather than the reflecting boundaries of Ref. 26), as shown in Fig. 10. This choice is the simplest consistent with Chandrasekhar's analysis. Because his choice of rigid horizontal boundaries (with vanishing there) corresponds to an aspect ratio within a percent of 2, we adopted that choice for a numerical test of the smoothed-particle method.

The lateral periodic boundaries are straightforward to implement, and require no discussion. For reproducibility, the top-and-bottom boundary conditions need to be discussed in some detail. We consider the three steps involved in solving the smoothed-particle equations of motion: (i) calculation of densities \( \rho_i \), (ii) calculation of gradients \( \{(\nabla \rho)_i; (\nabla T)_i\} \), (iii) calculation of time derivatives \( \{\dot{\rho}_i; \dot{T}_i\} \).

First, the densities of bulk particles inside the container include contributions from reflected image particles, as shown in Fig. 10. Next, contributions from the images are used in the calculation of the velocity and temperature gradients. In the bulk fluid, these gradients can best be calculated by starting from the identity

\[ \rho \nabla f = \nabla (\rho f) - f \nabla \rho , \]  

where \( f \) can represent either the velocity \( \mathbf{v} \) or the temperature \( T \). This choice leads to the highly desirable absence of flux contributions between smooth particles having the same values of \( f \). Expressing the two gradients, on the right-hand side, in terms of the smoothed-particle weighting function \( \omega \), and dividing by a symmetrized density \( \rho_{ij} \), leads to the following definitions:

\[ \{(\nabla \rho)_i = m \sum_j [\nabla_i w_{ij} (v_j - v_i)]/\rho_{ij} , \quad (\nabla T)_i = m \sum_j [\nabla_i w_{ij} (T_j - T_i)]/\rho_{ij} \} ; \quad w_{ij} = \omega (r_{ij}) , \]  

where \( \nabla \mathbf{v} \) is a second-rank tensor, \( \nabla T \) is a vector, and where we can choose either the arithmetic-mean density, \( \rho_{ij} = (\rho_i + \rho_j) / 2 \) or the geometric-mean density, \( \rho_{ij} = (\rho_i \rho_j)^{1/2} \). These choices lead to very similar results. For the reflected boundary contributions of \([i,j]\), the images of \([i,j]\), we include all pairs of contributions \([\bar{i},j]\) and \([j,\bar{i}]\) for which a particle-image pair has a separation less than the range of the weighting function. See again Fig. 10, in which image particles are indicated by open circles. For the image of particle \(i\), \( v_{\bar{i}}\), and \( T_{\bar{i}}\) are taken equal to the \textit{boundary} values rather than to the bulk values \( v_i\) and \( T_i\).

The equations of motion are based on a different identity,

\[ (\nabla f)/\rho = \nabla (f / \rho) + (f / \rho^2) (\nabla \rho) , \]  

where \( f \) can represent either the velocity \( \mathbf{v} \) or the internal energy \( e \). This choice is motivated by the fact that it leads to the conservation of \( f \) in the interaction of particle pairs. For smoothed particles in the bulk fluid, the corresponding equations of motion are
\[
\frac{dv_i}{dt} = \sum [(m \sigma / \rho^2)_j + (m \sigma / \rho^2)_i] \cdot \nabla_i w_{ij}.
\] (6.7)

The conductive contribution to the energy change has a similar form:

\[
\left( \frac{de_i}{dt} \right)_{\text{conduction}} = -\sum [(m Q / \rho^2)_j + (m Q / \rho^2)_i] \cdot \nabla_i w_{ij},
\] (6.8)

where \( Q \) is the heat flux vector, \(-\kappa \nabla T\). In these cases, the reflected image values of the stress tensor and the heat flux vector for \([i,j]\) are taken equal to the corresponding bulk values of particles \([i,j]\). In calculating the smoothed-particle boundary contribution to the compressive energy change, \(pde_i / dt = \sigma : \nabla v\), the image stresses are equal to the bulk stresses while the image velocities are given by the boundary values.

In relatively small-scale simulations of Rayleigh-Bénard flow, with 800 smoothed particles, we found that the flow field, shown in Fig. 10, was essentially independent of the "transport coefficients." We used state-independent Newtonian shear viscosity and Fourier heat conductivity throughout our work. With the three choices \(\eta/\rho = D = \kappa/(\rho C_v) = \{0.10, 0.15, 0.20\}(\varepsilon/m)^{1/2}\sigma_g\), the flow fields are statistically indistinguishable from one another, and correspond to a kinetic temperature of \(\sim 0.004\varepsilon/k\). This indicates that the intrinsic viscosity of the Lucy flow, though evidently less than our estimate for an energy \(E = N\varepsilon/2\), is still sufficiently great to exceed the specified viscosity, and dominates the flow. To emphasize this point, we carried out a simulation with the viscosity set equal to zero. (Thermal conductivity is still required, in order to drive the flow.) Again rolls formed, though irregularly and many in number, suggesting the presence of viscous dissipation in the smooth-particle model of an inviscid fluid.

A slightly larger system, with 5000 particles, is already sufficiently large to give a good representation of the macroscopic flow, accurate to a few percent. Figure 11 shows two flows, at Rayleigh numbers of 40 000 and 10 000. In order to compare these flows to the predictions of continuum mechanics, we have solved the complete compressible continuum equations on a variety of rectangular grids, using centered space differences and the fourth-order Runge-Kutta method to integrate \(\partial \rho / \partial t\), \(\partial v / \partial t\), and \(\partial e / \partial t\) to a fully converged steady state.

After several failed efforts, we found that a square grid, with \(v\), \(e\) evaluated at the grid points and \(\rho\), \(\nabla v\), \(\nabla e\), \(\sigma\), and \(Q\) evaluated at the squares' centers provided a robust and stable scheme. A fully converged centered-
difference flow field for a Rayleigh number of 10,000, corresponding to the lower illustration in Fig. 11, appears as Fig. 12. The agreement found is quite satisfactory. See the figure captions. Though smooth particles can easily produce Rayleigh-Bénard flows with a convincing appearance, using fewer particles than required by molecular dynamics simulations, quantitative results, in two dimensions, require on the order of thousands of smooth particles for velocity errors of order a few percent.

VII. CONCLUSIONS

Shear flows for the long-ranged and relatively soft Lucy potential are well described by the model of a Newtonian viscous fluid in two space dimensions. There is an interesting instability transition at relatively high energy, which deserves further study and analysis. Finite flow velocities guarantee a finite transport coefficient, even in two dimensions. The viscosities we find are essentially independent of system size and strain rate within the precision of the computer simulations. There is soon-to-be published support for this view in Green-Kubo simulations carried out by others [20]. Bocquet and Barrat, who have studied the effect of boundary conditions on transport in three dimensions [22], are now studying boundary effects in two dimensions [21]. Smooth-particle applied mechanics, which closely resembles molecular dynamics, can be used to solve continuum flow problems with fewer particles than are required for the atomistic simulations, though quantitative agreement still requires thousands of particles. See Ref. [9] for additional examples. The unusual size dependence of continuum Rayleigh-Bénard simulations, carried out with smooth-particle applied mechanics, can be understood in terms of the intrinsic viscosity due to the smooth-particle weighting function, characterized here.

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[21] L. Bocquet (private communication).